## SWITCHMODE SERIES NPN <br> SILICON POWER <br> TRANSISTORS

## - DESCRIPTION

The MJE13009 is designed for high-voltage, high-speed power switching inductive circuits where fall time is critical. They are particularly suited for 115 and 220 V switch mode applications such as Switching Regulators, Inverters, Motor Controls, Solenoid/Relay drivers and Deflection circuits.

## - FEATURES

* $V_{\text {ceo }} 400 \mathrm{~V}$ and 300 V
* Reverse Bias SOA with Inductive Loads @ $\mathrm{T}_{\mathrm{C}}=100^{\circ} \mathrm{C}$
* Inductive Switching Matrix $3 \sim 12 \mathrm{Amp}, 25$ and $100^{\circ} \mathrm{C}$ tc @ $8 \mathrm{~A}, 100^{\circ} \mathrm{C}$ is 120 ns (Typ).
* 700 V Blocking Capability
* SOA and Switching Applications Information.

*Pb-free plating product number:MJE13009L
- ORDERING INFORMATION

| Order Number |  | Package | Pin Assignment |  |  | Packing |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Normal | Lead Free Plating |  | 1 | 2 | 3 |  |
| MJE13009-TA3-T | MJE13009L-TA3-T | TO-220 | B | C | E | Tube |
| MJE13009-TF3-T | MJE13009L-TF3-T | TO-220F | B | C | E | Tube |
| MJE13009-T3P-T | MJE13009L-T3P-T | TO-3P | B | C | E | Tube |


|  | (1)Packing Type <br> (2)Package Type <br> (3)Lead Plating | (1) T: Tube <br> (2) TA3: TO-220, TF3: TO-220F, T3P: TO-3P <br> (3) L: Lead Free Plating, Blank: $\mathrm{Pb} / \mathrm{Sn}$ |
| :---: | :---: | :---: |

- ABSOLUTE MAXIMUM RATINGS $\left(\mathrm{Ta}=25^{\circ} \mathrm{C}\right)$

| PARAMETER |  | SYMBOL | RATINGS | UNIT |
| :---: | :---: | :---: | :---: | :---: |
| Collector-Emitter Voltage |  | $\mathrm{V}_{\text {CEO }}$ | 400 | V |
| Collector-Emitter Voltage ( $\mathrm{V}_{\text {BE }}=-1.5 \mathrm{~V}$ ) |  | $\mathrm{V}_{\text {CEV }}$ | 700 | V |
| Emitter Base Voltage |  | $V_{\text {Ebo }}$ | 9 | V |
| Collector Current | Continuous | Ic | 12 | A |
|  | Peak* | $\mathrm{I}_{\text {CM }}$ | 24 |  |
| Base Current | Continuous | $\mathrm{IB}_{B}$ | 6 | A |
|  | Peak* | $\mathrm{I}_{\text {BM }}$ | 12 |  |
| Emitter Current | Continuous | $\mathrm{I}_{\mathrm{E}}$ | 18 | A |
|  | Peak* | $\mathrm{I}_{\mathrm{Em}}$ | 36 |  |
| Total Power Dissipation @ Ta $=25^{\circ} \mathrm{C}$ Derate above $25^{\circ} \mathrm{C}$ |  | $P_{\text {D }}$ | 2 | W |
|  |  | 16 | $\mathrm{mW} /{ }^{\circ} \mathrm{C}$ |  |
| Total Power Dissipation @ $\mathrm{T}_{\mathrm{C}}=25^{\circ} \mathrm{C}$ Derate above $25^{\circ} \mathrm{C}$ |  |  | PD | 100 | W |
|  |  | 800 |  | $\mathrm{mW} /{ }^{\circ} \mathrm{C}$ |
| Junction Temperature |  | TJ | +150 | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature |  | $\mathrm{T}_{\text {STG }}$ | $-40 \sim+150$ | ${ }^{\circ} \mathrm{C}$ |

Note: 1. Pulse Test: Pulse Width $=5 \mathrm{~ms}$, Duty Cycle $\leq 10 \%$
2. Absolute maximum ratings are those values beyond which the device could be permanently damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.

- THERMAL DATA

| PARAMETER | SYMBOL | RATINGS | UNIT |
| :--- | :---: | :---: | :---: |
| Thermal Resistance Junction to Ambient | $\theta_{\text {JA }}$ | 54 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Thermal Resistance Junction to Case | $\theta_{\mathrm{Jc}}$ | 4 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

E ELECTRICAL CHARACTERISTICS ( $\mathrm{T}_{\mathrm{C}}=25^{\circ} \mathrm{C}$, unless otherwise specified.)

| PARAMETER | SYMBOL | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| *OFF CHARACTERISTICS |  |  |  |  |  |  |
| Collector- Emitter Sustaining Voltage | $\mathrm{V}_{\text {CEO }}$ | $\mathrm{I}_{\mathrm{C}}=10 \mathrm{~mA}, \mathrm{I}_{\mathrm{B}}=0$ | 400 |  |  | V |
| Collector Cutoff Current $\mathrm{V}_{\text {Cbo }}=$ Rated Value | $I_{\text {cev }}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{BE}(\mathrm{OFF})}=1.5 \mathrm{Vdc} \\ & \mathrm{~V}_{\mathrm{BE}(\mathrm{OFF})}=1.5 \mathrm{Vdc}, \mathrm{~T}_{\mathrm{C}}=100^{\circ} \mathrm{C} \end{aligned}$ |  |  | 1 5 | mA |
| Emitter Cutoff Current | $\mathrm{I}_{\text {Ebo }}$ | $V_{E B}=9 \mathrm{Vdc}, \mathrm{I}_{\mathrm{C}}=0$ |  |  | 1 | mA |

*ON CHARACTERISTICS

| DC Current Gain | $\mathrm{h}_{\text {FE1 }}$ | $\mathrm{I}_{\mathrm{C}}=5 \mathrm{~A}, \mathrm{~V}_{\text {CE }}=5 \mathrm{~V}$ | 40 |  |
| :---: | :---: | :---: | :---: | :---: |
|  | $\mathrm{h}_{\text {FE } 2}$ | $\mathrm{I}_{\mathrm{C}}=8 \mathrm{~A}, \mathrm{~V}_{C E}=5 \mathrm{~V}$ | 30 |  |
| Current-Emitter Saturation Voltage | $\mathrm{V}_{\text {CE(SAT) }}$ | $\mathrm{IC}_{\mathrm{C}}=5 \mathrm{~A}, \mathrm{I}_{\mathrm{B}}=1 \mathrm{~A}$ | 1 | V |
|  |  | $\mathrm{I}_{\mathrm{C}}=8 \mathrm{~A}, \mathrm{I}_{\mathrm{B}}=1.6 \mathrm{~A}$ | 1.5 | V |
|  |  | $\mathrm{I}_{\mathrm{C}}=12 \mathrm{~A}, \mathrm{I}_{\mathrm{B}}=3 \mathrm{~A}$ | 3 | V |
|  |  | $\mathrm{I}_{\mathrm{C}}=8 \mathrm{~A}, \mathrm{I}_{\mathrm{B}}=1.6 \mathrm{~A}, \mathrm{~T}_{\mathrm{C}}=100^{\circ} \mathrm{C}$ | 2 | V |
| Base-Emitter Saturation Voltage | $V_{\text {be(SAT) }}$ | $\mathrm{I}_{\mathrm{C}}=5 \mathrm{~A}, \mathrm{I}_{\mathrm{B}}=1 \mathrm{~A}$ | 1.2 | V |
|  |  | $\mathrm{I}_{\mathrm{C}}=8 \mathrm{~A}, \mathrm{I}_{\mathrm{B}}=1.6 \mathrm{~A}$ | 1.6 | V |
|  |  | $\mathrm{I}_{\mathrm{C}}=8 \mathrm{~A}, \mathrm{I}_{\mathrm{B}}=1.6 \mathrm{~A}, \mathrm{~T}_{\mathrm{C}}=100^{\circ} \mathrm{C}$ | 1.5 | V |

## DYNAMIC CHARACTERISTICS

| Transition frequency | $\mathrm{f}_{\mathrm{T}}$ | $\mathrm{I}_{\mathrm{C}}=500 \mathrm{~mA}, \mathrm{~V}_{\mathrm{CE}}=10 \mathrm{~V}, \mathrm{f}=1 \mathrm{MHz}$ | 4 |  |  | MHz |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Output Capacitance | $\mathrm{C}_{\mathrm{ob}}$ | $\mathrm{V}_{\mathrm{CB}}=10 \mathrm{~V}, \mathrm{I}_{\mathrm{E}}=0, \mathrm{f}=0.1 \mathrm{MHz}$ |  | 180 |  | pF |

SWITCHING CHARACTERISTICS (Resistive Load, Table 1)

| Delay Time | tDLY | $\begin{aligned} & \mathrm{V}_{\mathrm{CC}}=125 \mathrm{Vdc}, \mathrm{I}_{\mathrm{C}}=8 \mathrm{~A} \\ & \mathrm{I}_{\mathrm{B} 1}=\mathrm{I}_{\mathrm{B} 2}=1.6 \mathrm{~A}, \mathrm{t}_{\mathrm{P}}=25 \mu \mathrm{~s} \\ & \text { Duty Cycle } \leq 1 \% \end{aligned}$ | 0.06 | 0.1 | $\mu \mathrm{s}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Rise Time | $t_{R}$ |  | 0.45 | 1 | $\mu \mathrm{S}$ |
| Storage Time | $\mathrm{t}_{\text {s }}$ |  | 1.3 | 3 | $\mu \mathrm{S}$ |
| Fall Time | $\mathrm{t}_{\mathrm{F}}$ |  | 0.2 | 0.7 | $\mu \mathrm{s}$ |
| Inductive Load, Clamped (Table 1, Figure 13) |  |  |  |  |  |
| Voltage Storage Time | $\mathrm{t}_{5}$ | $\mathrm{IC}_{\mathrm{C}}=8 \mathrm{~A}, \mathrm{~V}_{\text {clamp }}=300 \mathrm{~V}, \mathrm{I}_{\mathrm{B} 1}=1.6 \mathrm{~A}$ | 0.92 | 2.3 | $\mu \mathrm{s}$ |
| Crossover Time | $\mathrm{t}_{\mathrm{c}}$ | $\mathrm{V}_{\mathrm{BE}(\mathrm{OFF})}=5 \mathrm{~V}, \mathrm{~T}_{\mathrm{C}}=100^{\circ} \mathrm{C}$ | 0.12 | 0.7 | $\mu \mathrm{s}$ |

*Pulse Test: Pulse Wieth $=300 \mu \mathrm{~s}$, Duty Cycle $=2 \%$

TABLE 1. TEST CONDITIONS FOR DYNAMIC PERFORMANCE

| REVERSE BIAS SAFE OPERATING AREA AND INDUCTIVE SWITCHING |  | RESISTIVE SWITCHING |
| :---: | :---: | :---: |
|  |  |  |
|  | Coil Data: <br> $\begin{array}{lll}\text { Ferroxcube Core \#6656 } & \text { GAP for } 200 \mu \mathrm{H} / 20 \mathrm{~A} & \mathrm{~V}_{\mathrm{CC}}=20 \mathrm{~V} \\ \text { Full Bobbin ( } 16 \text { Turns) } \# 16 & \mathrm{~L}_{\text {coil }}=200 \mu \mathrm{H} & \mathrm{V}_{\text {clamp }}=300 \mathrm{Vdc}\end{array}$ | $\begin{aligned} & \mathrm{V}_{\mathrm{CC}}=125 \mathrm{~V} \\ & \mathrm{R}_{\mathrm{C}}=15 \Omega \\ & \mathrm{D} 1=1 \mathrm{~N} 5820 \text { or Equiv. } \\ & \mathrm{R}_{\mathrm{B}}=\Omega \end{aligned}$ |
|  | OUTPUT WAVEFORMS <br> t1 ADJUSTED TO OBTAIN IC $\begin{aligned} & \mathrm{t}_{1} \approx \frac{\mathrm{~L}_{\text {coil }}\left(\mathrm{I}_{\mathrm{CM}}\right)}{\mathrm{V}_{\mathrm{CC}}} \\ & \mathrm{t}_{2} \approx \frac{\mathrm{~L}_{\text {coil }}\left(\mathrm{I}_{\mathrm{cM}}\right)}{\mathrm{V}_{\text {clamp }}} \end{aligned}$ <br> Test Equipment Scope-Tektronics 475 or Equivalent | $\mathrm{t}_{\mathrm{R}}, \mathrm{t}_{\mathrm{F}}<10 \mathrm{~ns}$ Duty Cycle = 1.0\% $\mathrm{R}_{\mathrm{B}}$ and $\mathrm{R}_{\mathrm{C}}$ adjusted for desired $I_{B}$ and $I_{C}$ |

TABLE 2. APPLICATIONS EXAMPLES OF SWITCHING CIRCUITS
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■ TABLE 3. TYPICAL INDUCTIVE SWITCHING PERFORMANCE

| $\mathrm{I}_{\mathrm{C}}(\mathrm{A})$ | $\mathrm{T}_{\mathrm{C}}\left({ }^{\circ} \mathrm{C}\right)$ | $\mathrm{t}_{\mathrm{sv}}(\mathrm{ns})$ | $\mathrm{t}_{\mathrm{v}}(\mathrm{ns})$ | $\mathrm{t}_{\mathrm{fi}}(\mathrm{ns})$ | $\mathrm{t}_{\mathrm{t}}(\mathrm{ns})$ | $\mathrm{t}_{\mathrm{c}}(\mathrm{ns})$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 3 | 25 | 770 | 100 | 150 | 200 | 240 |
|  | 100 | 1000 | 230 | 160 | 200 | 320 |
| 5 | 25 | 630 | 72 | 26 | 10 | 100 |
|  | 100 | 820 | 100 | 55 | 30 | 180 |
| 8 | 25 | 720 | 55 | 27 | 2 | 77 |
|  | 100 | 920 | 70 | 50 | 8 | 120 |
| 12 | 25 | 640 | 20 | 17 | 2 | 41 |
|  | 100 | 800 | 32 | 24 | 4 | 54 |

■ SWITCHING TIME NOTES
In resistive switching circuits, rise, fall, and storage times have been defined and apply to both current and voltage
waveforms since they are in phase. However, for inductive loads which are common to SWITCHMODE power supplies and hammer drivers, current and voltage waveforms are not in phase. Therefore, separate measurements must be made on each waveform to determine the total switching time. For this reason, the following new terms have been defined.
$\mathrm{t}_{\mathrm{sv}}=$ Voltage Storage Time, $90 \% \mathrm{I}_{\mathrm{B} 1}$ to $10 \% \mathrm{~V}_{\text {CEm }}$
$\mathrm{t}_{\mathrm{rv}}=$ Voltage Rise Time, $10-90 \% \mathrm{~V}_{\text {CEm }}$
$\mathrm{t}_{\mathrm{fi}}=$ Current Fall Time, 90-10\% Icm
$\mathrm{t}_{\mathrm{ti}}=$ Current Tail, $10-2 \% \mathrm{Icm}_{\mathrm{cm}}$
$\mathrm{t}_{\mathrm{c}}=$ Crossover Time, $10 \% \mathrm{~V}_{\text {CEM }}$ to $10 \% \mathrm{I}_{\text {CM }}$
An enlarged portion of the turn-off waveforms is shown in Figure 13 to aid in the visual identity of these terms.
For the designer, there is minimal switching loss during storage time and the predominant switching power losses occur during the crossover interval and can be obtained using the standard equation from AN-222:
$P_{\text {SWT }}=1 / 2 \mathrm{~V}_{\mathrm{CCl}} \mathrm{I}_{\mathrm{c}}\left(\mathrm{t}_{\mathrm{c}}\right) \mathrm{f}$
Typical inductive switching waveforms are shown in Figure 14. In general, $t_{r v}+t_{f i} \approx t_{c}$. However, at lower test currents this relationship may not be valid.

As is common with most switching transistors, resistive switching is specified at $25^{\circ} \mathrm{C}$ and has become a benchmark for designers. However, for designers of high frequency converter circuits, the user oriented specifications which make this a "SWITCHMODE" transistor are the inductive switching speeds ( $\mathrm{t}_{\mathrm{c}}$ and $\mathrm{t}_{\mathrm{sv}}$ ) which are guaranteed at $100^{\circ} \mathrm{C}$.

TYPICAL CHARATERISTICS

Figure 1. Forward Bias Safe Operating Area


Figure 3. Forward Bias Power Derating


Figure 2. Reverse Bias Switching Safe Operating Area


There are two limitations on the power handling ability of a transistor: average junction temperature and second breakdown. Safe operating area curves indicate $\mathrm{I}_{\mathrm{C}}-\mathrm{V}_{\mathrm{CE}}$ limits of the transistor that must be observed for reliable operation; i.e., the transistor must not be subjected to greater dissipation than the curves indicate.
The data of Figure 1 is based on $T_{C}=25^{\circ} \mathrm{C} ; \mathrm{T}_{\mathrm{J}(\mathrm{pk})}$ is variable depending on power level. Second breakdown pulse limits are valid for duty cycles to $10 \%$ but must be derated when $\mathrm{T}_{\mathrm{C}} \geq 25^{\circ} \mathrm{C}$. Second breakdown limitations do not derate the same as thermal limitations. Allowable current at the voltages shown on Figure 1 may be found at any case temperature by using the appropriate curve on Figure 3.
$\mathrm{T}_{\mathrm{J}(\mathrm{pk})}$ may be calculated from the data in Figure 4. At high case temperatures, thermal limitations will reduce the power that can be handled to values less than the limitations imposed by second breakdown. Use of reverse biased safe operating area data (Figure 2) is discussed in the applications information section.

Figure 4. Typical Thermal Response $\left[Z_{\theta\lrcorner c}(t)\right]$


- TYPICAL CHARACTERISTICS (Cont.)

Figure 5. DC Current Gain


Figure 7. Base - Emitter Saturation Voltage


Figure 9. Collector Cutoff Region


Figure 6. Collector Saturation Region


Figure 8. Collector - Emitter Saturation Voltage


Figure 10. Capacitance


RESISTIVE SWITCHING PERFORMANCE

Figure 11. Turn - On Time


Figure 12. Turn - Off Time


Figure 13. Typical Inductive Switching Waveforms (at 300 V and 12 A with $\mathrm{I}_{\mathrm{B} 1}=2.4 \mathrm{~A}$ and $\mathrm{V}_{\mathrm{BE}(\text { off })}=5 \mathrm{~V}$ )


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